Appendix 1: Source Code for Sample Implementation of Access Delay Reduction Algorithm

This section contains sample C++ source code for a floating-point version of the Access Delay Reduction algorithm. 5 files are listed.

File	Description
pseudocode.c	Pseudo C++ code that shows how to call the ADR algorithm in an application. No implementations are given for many of the functions called in this code as they are system dependent.
adr.h	Header file for the Access Delay Reduction algorithm. Includes declarations for both the public and private parts of the class. Internally, this class uses the CircularBuffer class.
adr.c	Implementation of the Access Delay Reduction algorithm. This file contains the heart of the algorithm and is the most important file included here.
circularbuffer.h	Include file for a circular First In First Out (FIFO) buffer. The CircularBuffer is used internally by adr.c. It is not called directly by the user and is included to clarify its use by the AccessDelayReduducer class.
circularbuffer.c	Implementation of the circular buffer. This file includes "libcoder.h" which is not shown here. The only function declared in libcoder.h is the error function, which halts the system on catastrophic errors.

```
File: pseudocode.c
  1 /*
    * Copyright (c) 1999-2000 AT&T Corp.
  2
     * All Rights Reserved.
  5 #include <circularbuffer.h>
  6 #include <vad.h>
  7 #include <adr.h>
  8 /*
  9
     * pseudo code for main processing loop with Access Delay Reduction algorithm.
 10
     * Read a frame's worth of audio, give it to both the VAD and ADR. When
     * the VAD detects onset of activity, request a transmission channel. In
 12
     * the mean time the ADR buffers the speech. After the access delay, the
 13
     * ADR time-scales the beginning of the talkspurt until the access delay
     * is gone. At the end of the talkspurt, the transmit channel is freed.
     */
 15
 16 void processloop()
 17 (
 18
       int
                           framesz = 160;
                                                /* 20 msec at 8 KHz */
 19
       Float
                           y[160];
 20
       bool
                           activity, oldactivity = false;
 21
       bool
                           adrdata, oldadrdata = false;
```

```
vad(8000, 160);
22
     Vad
     AccessDelayReducer
                           adr(8000, 20., 60., 500.);
23
      while (readinputframe(y, framesz)) (
24
             activity = vad.activity(y);
25
             /* request transmission channel at activity onset */
26
             if (activity && !oldactivity)
27
                    request_tx_channel();
28
             adrdata = adr.newframe(y, y, activity);
29
30
             if (adrdata)
                    encode and xmit(y, framesz);
31
             /* free channel when ADR buffer has drained */
32
             if (!adrdata && oldadrdata)
33
                    free tx channel();
34
35
             oldactivity = activity;
             oldadrdata = adrdata;
36
37
38 }
```

Pseudocode.c

The function processloop in pseudocode.c shows how the AccessDelayReducer class is used in an application. Here, we have decided to process the speech in increments of 160 samples, or 20 msec at 8 KHz sampling. On line 19 an array large enough to hold one frame's worth of floats is declared. The "Float" type is defined as a float with a typedef in the file circularbuffer.h. The bools on lines 20 and 21 keep track of the current and previous state of both the VAD and the ADR. An inactive to active transition detected by the VAD is used to request a transmission channel on lines 27 and 28. On lines 33-34, the end of available data for a talkspurt is used to relinquish the transmission channel. The constructor for the VAD on line 22 sets the VAD frame size to 160 samples and the samplerate to 8 KHz. The constructor call to the AccessDelayReducer on line 23 sets the samplerate to 8 KHz, the frame size to 20 msec, the access delay to 60 msec, and the interval for the time-scaling to 500 msec.

The loop on lines 24-37 reads in a frame of data and processes it. First, the VAD determines if there is activity on line 25. Next the frame is given to the ADR on line 29. The first argument is the input frame and the second argument is the output frame. In this example, the output from the ADR is placed in the same buffer used for input. The speech is buffered and delayed internally by the ADR. The call to newframe returns true if the output frame contains speech that should be transmitted (there is activity in it) and false otherwise. At the first few frames after an inactive to active transition in the VAD, e.g. for the duration of the access delay, newframe returns false even though the input frames contain active speech. After the access delay is over, the speech at the start of the talkspurt is returned. Newframe then starts time-scale compressing the speech until the access delay is removed.

Since the ADR may leave some residual delay or the talkspurt may be too short for the ADR to finish time-scaling, the output of the ADR determines when the transmission channel is returned rather than the VAD. All the active speech buffered in the ADR must be output before channel is returned.

```
File: adr.h
1 /*
```

```
• Copyright (c) 15-9-2000 AT&T Corp.
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    Performing time-scaling compression at the start of a talkspurt

   · in systems where there is access delay for channel allocation such
   * as Voice over EDGE.
   •/
8
9 class AccessDelayReducer {
10 public:
11
            AccessDelayReducer(int srate, Float framesizems,
                   Float accessdelayms, Float timescaleintervalms);
12
13
             ~AccessDelayReducer();
            newframe(Float *in, Float *out, bool active);
14
     bool
15 protected:
     Float frameszmsec: /* frame size in msec */
16
     Float sysdelaymsec: /* system contention delay, msec */
17
                                 /* interval for timescaling, msec */
18
     Float timescalemsec;
      Float targetaccum; /* target accumulator, samples */
19
                         /* target increment, samples */
20
     Float targetincr;
                          /* samplerate, Hz */
21
      int
             samplerate;
                          /* frame size in samples */
22
      int
             framesz;
                          /* frames in current talk spurt */
23
     int
             activelen;
                          /* system contention delay, frames */
24
      int
             sysdelayf;
                         /* system delay, samples */
25
      int
             sysdelay;
                           /* current delay, samples */
      int
             curdelay;
26
             targetdelay; /* target delay, samples */
27
      int
                          /* timescaling interval, frames */
28
      int
             timescalef;
             timescalefirstf;/* first frame to start timescaling */
29
      int
                                  /* last frame to start timescaling */
30
      int
             timescalelastf;
                           /* decimation factor */
31
      int
             ndec;
             pitchmin;
32
      int
                          /* minimum pitch */
                           /* maximum pitch */
33
      int
             pitchmax;
                           /* pitch difference */
34
      int
             pitchdiff;
                           /* correlation length */
35
      int
             corrlen;
                           /* length of correlation buffer */
36
      int
             corrbuflen;
                           *outbuf;/* output buffer */
37
      CircularBuffer
                           /* temporary scratch buffer */
38
      Float *tmpbuf;
                           /* input buffer */
39
      Float *corrbuf;
             findbestmatch();
40
      int
             updatecorrbuf(Float *s);
41
      void
             removedelay(Float *in, int pitch);
42
      void
43
      void
             overlapadd(Float *1, Float *r, Float *o, int cnt);
44
      void
             idle();
             copy(Float *f, Float *t, int cnt);
45
      void
             zero(Float *s, int cnt);
46
      void
47 );
File: adr.c
    * Copyright (c) 1999-2000 AT&T Corp.
    * All Rights Reserved.
  5 #include <math.h>
  6 #include "circularbuffer.h"
  7 #include "adr.h"
                                         /* minimum allowed pitch, 400 Hz */
                            .0025
  8 #define
             PITCH MIN
                            .015
                                         /* maximum allowed pitch, 66 Hz */
 9 #define
             PITCH MAX
                                         /* 2:1 decimation at 8kHz */
 10 #define
             NDEC 8K
                            2
             CORRMINPOWER ((Float)250.)/* minimum power */
CORRLEN .020 /* 20 msec correlation length */
 11 #define
 12 #define
             CORRLEN
```

```
13 /*
   . Constructor sets the samplerate, the frame size, the estimated access delay
14

    and the time-scaling interval. Appropriate length buffers are allocated

15
    * based on these parameters.
16
17
   • /
18 AccessDelayReducer::AccessDelayReducer(int srate, Float framesizems,
19
      Float accessdelayms, Float timescaleintervalms)
20 (
      samplerate = srate;
21
      frameszmsec = framesizems;
22
23
      sysdelaymsec = accessdelayms;
      timescalemsec = timescaleintervalms;
24
      ndec = (int)(NDEC_8K * samplerate / 8000.);
25
      pitchmin = (int)(PITCH MIN * samplerate);
26
     pitchmax = (int)(PITCH_MAX * samplerate);
27
      pitchdiff = pitchmax - pitchmin;
28
      corrlen = (int) (CORRLEN * samplerate);
29
      corrbuflen = corrlen + pitchmax;
30
      framesz = (int)(samplerate * frameszmsec * (Float).001);
31
      sysdelayf = (int)ceil(sysdelaymsec / frameszmsec);
32
      sysdelay = sysdelayf * framesz;
33
      timescalef = (int)ceil(timescalemsec / frameszmsec) + 1;
34
35
      timescalefirstf = sysdelayf + 1;
      timescalelastf = sysdelayf + timescalef;
36
      targetincr = (Float)sysdelay / (timescalef + 1);
37
38
      corrbuf = new Float(corrbuflen);
      outbuf = new CircularBuffer(framesz * (sysdelayf + 1));
39
40
      tmpbuf = new Float[pitchmax >> 2];
41
      activelen = 0;
42
      idle();
43 }
45 * Free allocated resources in destructor.
46 */
47 AccessDelayReducer::~AccessDelayReducer()
48 {
      delete [] tmpbuf;
49
      delete outbuf;
50
51
      delete [] corrbuf;
52 }
53 /*
    * main public function for time-scaling sppech at start of talkspurt.
54
    * Input is the speech from the audio port and active indicator from the
 55
   * VAD. Output is the speech delayed by the access delay, and then time-scaled
    * to get remove the delay at the start of the talksprt.
 57
    * Newframe returns true if the returned frame should be transmitted and
 58
      false if it should not be transmitted. For simulation purposes the
 59
    * returned frame of speech is set to zero if it should not be transmitted.
 60
    */
 61
 62 bool AccessDelayReducer::newframe(Float *in, Float *out, bool active)
 63 {
 64
      bool
             r;
 65
             pitch, cnt;
 66
      updatecorrbuf(in);
 67
       if (active) (
             /* simulate contention delay at start of utterance */
 68
              if (++activelen <= sysdelayf) {</pre>
 69
 70
                       if delayed samples still left from last utterance
 71
                      * flush it. This shouldn't happen since if there
 72
```

```
73
                        is some leftover delay, it should be
                                                                tput at
74
                      * the first frame where the VAD determines there is
75
                      no activity.
76
77
                    if (activelen == 1 && outbuf->filled())
78
                           outbuf->flush();
79
                     outbuf->write(in, framesz);
                     curdelay += framesz;
80
                     zero(out, framesz);
81
92
                     r = false;
83
              /* time-scale at start of utterance */
84
85
              else {
                     /* update the current amount we allow to timescale */
86
                     if (activelen <= timescalelastf) {</pre>
87
នន
                            /*
                             * boost at first frame so targetaccum is
89
90
                             * greater than pitchmin so its possible
91
                             * to time-scale at frame timescalefirstf.
92
                             * /
93
                            if (activelen == timescalefirstf)
94
                                   targetaccum = (Float)2. * targetincr;
95
                            else
                                   targetaccum += targetincr;
96
97
                            targetdelay = (int)targetaccum;
                            if (targetdelay > curdelay)
98
99
                                   targetdelay = curdelay;
100
                     }
101
102
                      * if the target for delay removal is larger than
103
                      * the minimum pitch, we can try to remove the delay.
                      * We still may not be able to do it yet if the
104
105
                      * estimated pitch is larger than the target delay.
                      * /
106
107
                     if (targetdelay >= pitchmin &&
108
                         (pitch = findbestmatch()) <= targetdelay) {</pre>
109
                            removedelay(in, pitch);
                            outbuf->read(out, framesz);
110
111
112
113
                      * either time-scaling isn't necessary, or not
114
                      * possible because not enough time has passed,
                      * or the current pitch is too long.
115
                      * If outcnt is 0, all the delay has been removed
116
                      * so we just copy the data from input to output.
117
                      * Otherwise, there is still delay in the system
118
                      * so the output must be buffered.
119
120
                     else if (outbuf->filled() == 0)
121
122
                            copy(in, out, framesz);
123
                     else {
124
                            outbuf->write(in, framesz);
125
                            outbuf->read(out, framesz);
126
127
                     r = true;
128
129
130
       /* no speech activity detected */
131
       else (
              if (activelen != 0) {
132
                     activelen = 0;
133
134
                     idle();
135
```

```
/* if something left in delay buffer, output it
136
137
              cnt = outbuf->filled();
138
              if (cnt) {
139
                     if (cnt >= framesz)
140
                            cnt = framesz;
                     int left = framesz - cnt;
141
142
                     outbuf->read(out, cnt);
143
                     zero(&out[cnt], left);
144
                     if (outbuf->filled() == 0)
                           idle();
145
146
                     r = true;
147
              } else {
148
                     zero(out, framesz);
149
                     r = false;
150
              }
151
       }
152
       return r;
153 }
154 /* remove the delay by time-scale compressing the input */
155 void AccessDelayReducer::removedelay(Float *in, int pitch)
156 (
157
       int
              p2, pq, cnt, olacnt, ocnt;
158
       /* see if we can remove more than one pitch period at a time */
159
       p2 = pitch << 1;
160
       if (p2 <= targetdelay && p2 <= pitchmax)</pre>
161
              pitch = p2;
       pq = pitch >> 2;
162
163
       olacnt = pitch + pq;
       /* if the OLA fits in one frame, work directly on the input frame */
164
165
       if (olacnt <= framesz) (
166
              cnt = framesz - olacnt;
              outbuf->write(in, cnt);
167
              overlapadd(&in(cnt), &in(cnt+pitch), tmpbuf, pq);
168
169
              outbuf->write(tmpbuf, pq);
170
171
       /* Otherwise we have to copy some samples from the previous frame */
172
       else {
173
              cnt = olacnt - framesz;
174
              ocnt = pq - cnt;
              outbuf->peektail(tmpbuf, cnt);
175
                                                /* from previous frame tail */
176
              copy(in, &tmpbuf[cnt], ocnt);
                                                /* from current frame */
              overlapadd(tmpbuf, &in[framesz - pq], tmpbuf, pq);
177
178
              outbuf->replacetail(tmpbuf, cnt); /* replace old tail */
                                                /* write tail of OLA */
179
              outbuf->write(tmpbuf, ocnt);
180
       /* update the current delay variables */
181
182
       targetaccum -= (Float)pitch;
183
       targetdelay -= pitch;
184
       curdelay -= pitch;
185 }
186 /* Initialized the time-scaling variables */
187 void AccessDelayReducer::idle()
188 {
189
       curdelay = 0;
190
       targetdelay = 0;
191
       targetaccum = 0.;
192 }
193 /* Save a frames worth of new speech into the correlation buffer */
194 void AccessDelayReducer::updatecorrbuf(Float *s)
```

```
195 (
196
       int offset = corrbuflen - framesz;
197
       /* make room for new speech frame */
       copy(&corrbuf(corrbuflen - offset), corrbuf, offset);
198
       /* copy in the new frame */
199
       copy(s, &corrbuf(offset), framesz);
200
201 }
202 /*
203
     * Find the best match between the last segment of speech and
     * the previous speech in the correlation buffer.
204
     */
205
206 int AccessDelayReducer::findbestmatch()
207 {
208
       int
              i, j, k;
209
       int
              bestmatch;
210
       -Float bestcorr;
       Float corr;
                            /* correlation */
211
212
       Float energy;
                                   /* running energy */
                            /* scale correlation by average power */
       Float scale;
213
       Float *rp;
                            /* segment to match */
214
       Float *1;
215
216
       1 = &corrbuf(pitchmax);
217
       /* coarse search */
218
       rp = corrbuf;
219
       energy = 0.f;
220
       corr = 0.f;
       for (i = 0; i < corrlen; i += ndec) {
221
              energy += rp[i] * rp[i];
222
223
              corr += rp[i] * l[i];
224
       scale = energy;
225
       if (scale < CORRMINPOWER)
226
              scale = CORRMINPOWER;
227
       corr /= (Float)sqrt(scale);
228
229
       bestcorr = corr;
230
       bestmatch = 0;
231
        for (j = ndec; j <= pitchdiff; j += ndec) {</pre>
232
              energy -= rp(0) * rp(0);
              energy += rp(corrlen) * rp(corrlen);
233
              rp += ndec;
234
235
               corr = 0.f;
               for (i = 0; i < corrlen; i += ndec)</pre>
236
237
                     corr += rp(i) * l(i);
238
               scale = energy;
              if (scale < CORRMINPOWER)</pre>
239
240
                     scale = CORRMINPOWER;
 241
               corr /= (Float)sqrt(scale);
 242
               if (corr >= bestcorr) {
                      bestcorr = corr;
 243
 244
                     bestmatch = j;
 245
               }
 246
        /* fine search */
 247
 248
        j = bestmatch - (ndec - 1);
 249
        if (j < 0)
              j = 0;
 250
 251
        k = bestmatch + (ndec - 1);
 252
        if (k > pitchdiff)
 253
               k = pitchdiff;
 254 .
        rp = &corrbuf(j);
 255
        energy = 0.f;
```

```
256
       corr = 0.f;
       for (i = 0; i < corrlen; i++) {
257
258
             energy += rp[i] * rp[i];
259
             corr += rp[i] * l[i];
260
      1
      scale = energy;
261
262
       if (scale < CORRMINPOWER)
263
             scale = CORRMINPOWER;
       corr = corr / (Float)sqrt(scale);
264
265
      bestcorr = corr;
      bestmatch = j;
266
267
       for (j++; j \le k; j++) {
             energy -= rp[0] * rp[0];
268
269
             energy += rp(corrlen) * rp(corrlen);
270
             rp++;
271
             corr = 0.f;
272
             for (i = 0; i < corrlen; i++)
                    corr += rp[i] * l[i];
273
274
             scale = energy;
275
             if (scale < CORRMINPOWER)
276
                    scale = CORRMINPOWER;
277
             corr /= (Float)sqrt(scale);
278
             if (corr > bestcorr) {
279
                    bestcorr = corr;
280
                    bestmatch = j;
281
282
283
      return pitchmax - bestmatch;
284 }
285 /* Overlap add with triangular windows */
286 void AccessDelayReducer::overlapadd(Float *1, Float *r, Float *o, int cnt)
287 {
288
       Float incr = (Float)1. / cnt;
289
       Float lw = (Float)1. - incr;
      Float rw = incr;
290
       for (int i = 0; i < cnt; i++) {
291
             o[i] = lw * l[i] + rw * r[i];
292
293
             lw -= incr;
294
             rw += incr;
295
       }
296 }
297 void AccessDelayReducer::copy(Float *f, Float *t, int cnt)
298 (
299
       for (int i = 0; i < cnt; i++)
300
             t[i] = f[i];
301 }
302 void AccessDelayReducer::zero(Float *s, int cnt)
303 {
304
       for (int i = 0; i < cnt; i++)
305
             s[i] = (Float)0.;
306 l
File: circularbuffer.h
  1 /*
    * Copyright (c) 1999-2000 AT&T Corp.
  2
     * All Rights Reserved.
     * Circular buffer
    */
```

```
8 class CircularBuffer {
 9 public:
10
              CircularBuffer(int sz);
11
              ~CircularBuffer();
12
      void
             read(Float *f, int sz);
13
       void
             write(Float *f, int sz);
       void
              peekhead(Float *f, int sz);
14
15
       void
              peektail(Float *f, int sz);
             replacehead(Float *f, int sz);
replacetail(Float *f, int sz);
 16
       void
17
       void
18
       void
              flush();
19 ·
       void
              clear();
20
       int
           capacity()
                            { return buflen; }
 21
                            { return cnt; }
       int
              filled()
22 protected:
                                   /* buffer size */
23
       int
              buflen;
 24
       int
              cnt;
                            /* valid samples in buffer */
                            /* buffer */
       Float *buf;
25
 26
       Float *bufe;
                            /* buffer end */
 27
       Float *bufr;
                            /* buffer read pointer */
       Float *bufw;
                            /* buffer write pointer */
28
 29
       void copy(Float *f, Float *t, int cnt);
 30 };
File: circularbuffer.c
  1 /*
    * Copyright (c) 1999-2000 AT&T Corp.
    * All Rights Reserved.
  3
  4 */
  5 #include "libcoder.h"
  6 #include "circularbuffer.h"
  7 CircularBuffer::CircularBuffer(int sz)
  8 {
  9
       buflen = sz;
 10
       buf = new Float[buflen];
 11
       bufe = &buf[buflen];
 12
       flush();
 13 }
 14 CircularBuffer::~CircularBuffer()
 15 . (
 16
       delete [] buf;
 17 }
 18 /* flush all data from the buffer */
 19 void CircularBuffer::flush()
 20 (
       bufr = bufw = buf;
 21
 22
       cnt = 0;
 23 }
 24 /* fill the buffer with all zeros */
 25 void CircularBuffer::clear()
 26 (
 27
       int
              i;
 28
       bufr = bufw = buf;
 29
       cnt = buflen;
 30
       for (i = 0; i < buflen; i++)
 31
              buf[i] = 0.;
```

7 typedef float Flo

```
32 }
33 /*
34 * Save data in the buffer. Its legal to write more data to the buffer
35 * than it can hold. In this case just the latest data is kept and the
36 * read pointer is updated.
37 •/
38 void CircularBuffer::write(Float *f, int sz)
39 {
40
      int left;
      cnt += sz;
41
. 42
      do (
             left = bufe - bufw;
43
44
             if (left > sz)
 45
                    left = sz;
 46
             copy(f, bufw, left);
 47
             bufw += left;
 48
             if (bufw == bufe)
 49
                   bufw = buf;
 50
             sz -= left;
51
             f += left;
      ) while (sz);
52
53
 54
       * if more data has been written than can fit,
       \ ^{\star} update the read pointer so it reads the latest data.
55
56
 57
      if (cnt > buflen) (
58
             cnt = buflen;
59
             bufr = bufw;
 60
 61 }
 62 /* retrieve data from the buffer */
 63 void CircularBuffer::read(Float *f, int sz)
 64 {
 65
       if (sz > cnt)
             ::error("CircularBuffer::read: read too large");
 66
 67
      cnt -= sz;
 68
      int c = bufe - bufr;
 69
      if (sz < c) (
 70
             copy(bufr, f, sz);
 71
             bufr += sz;
 72
      } else {
 73
              int c2 = sz - c;
 74
              copy(bufr, f, c);
 75
             copy(buf, &f[c], c2);
 76
             bufr = &buf[c2];
 77
       }
 78 }
 79 /*
 80 * return the first sz samples at the head of
 81 * the buffer without modifying the buffer
 82 */
 83 void CircularBuffer::peekhead(Float *f, int sz)
 84 {
 85
       if (sz > cnt)
             ::error("CircularBuffer::peekhead: not enough data");
 86
 87
       int c = bufe - bufr;
 88
       if (sz \le c)
              copy(bufr, f, sz);
 89
 90
       else {
```

```
91
             copy (bul
 92 .
             copy(buf, &f[c], sz - c);
 93
       }
 94 }
 95 /* replace the first sz samples at the head of the buffer */
 96 void CircularBuffer::replacehead(Float *f, int sz)
 97 (
 98
       if (sz > cnt)
 99
             ::error("CircularBuffer::replacehead: not enough data");
100
      int c = bufe - bufr;
101
      if (sz <= c)
102
             copy(f, bufr, sz);
      else {
103
104
             copy(f, bufr, c);
105
             copy(&f(c), buf, sz - c);
106
       }
107 }
109 * return the last sz samples in the tail of
110
    * the buffer without modifying the buffer
111
112 void CircularBuffer::peektail(Float *f, int sz)
113 {
114
       if (sz > cnt)
115
             ::error("CircularBuffer::peektail: not enough data");
116
       int fromstart = bufw - buf;
117
       if (sz > fromstart) {
118
             int c = sz - fromstart;
             copy(bufe - c, f, c);
119
120
             f += c;
121
             sz -= c;
122
       }
      copy(bufw - sz, f, sz);
123
124 }
125 /* replace the last sz samples in the tail of the buffer */
126 void CircularBuffer::replacetail(Float *f, int sz)
127 (
128
      if (sz > cnt)
              ::error("CircularBuffer::replacetail: not enough data");
129
130
       int fromstart = bufw - buf;
131
       if (sz > fromstart) (
132
             int c = sz - fromstart;
133
             copy(f, bufe - c, c);
134
             f += c;
135
             sz -= c;
136
137
       copy(f, bufw - sz, sz);
138 }
139 void CircularBuffer::copy(Float *f, Float *t, int cnt)
140 {
141
       for (int i = 0; i < cnt; i++)
142
             t[i] = f[i];
143 }
```